

to Rheslogy

Interconversions



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The Abbott Guide to Rheology Prof Steven Abbott

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Preface

"Maybe we should check out the rheology of this system" is the sort of sentence that can create panic and alarm in many people. Rheology has a reputation $\mathfrak{A} \circ \mathfrak{A} \circ$

There are some excellent books on general rheology. I have especially valued Thomas Mezger's *Rheology Handbook* as he writes as an expert who knows his subject, his equipment and his audience well. This guide in no way wishes to compete with the 400pp of Mezger's book. There are also many excellent $a[[\ [] \cdot [] \cdot]^{a}, a =]^{a} - [a^{[[*^ \cdot] a} - a^{a}] = 0]^{a} - [a^{[[*^ \cdot] a} - a^{a}] = 0]^{a} - [a^{[[*^ \cdot] a} - a^{a}] = 0]^{a} - a^{a}] = 0$ *Principles, Measurements and Applications* or Jan Mewis and Norman Wagner's *Colloidal Suspension Rheology,* from each of which I have learned a great deal. And the TA Instruments Webinar Series on YouTube is a great way to learn the details of rheological techniques from experts.

So this guide attempts to describe the problems we need to solve, along with the appropriate bit of rheology that helps provide the answers. In order to describe the problem we have to introduce some key ideas such as entanglement and relaxation times that are not at all hard but which are generally unknown or under-appreciated.

To make life easier for the reader and for myself (after all, I need to understand $c@i \cdot c \in a \cdot (||)^{1/2} \otimes c \cdot (|a|) \otimes (|a|)$

Along the way, the guide will point out why rheologists have created so much confusion for the rest of us, and, via apps, bring some order to that confusion. If any real rheologist reads this guide, maybe they will see the world through our non-expert eyes and try, in future, to be less confusing. I will also point out some $@^* + a_* + a_$

Because I am not a rheologist and have always struggled with rheology, I have had to rely on the wise input from a number of world-class rheology experts. I am especially grateful to one expert who, after glancing at an early prototype $[~U_{\&\&ci\&@}]$ $U_{@}^{[[*^{*} & @iii]} (c' & ,)^{E} c^{A} c^{A}] c^{[i]} c@^{A} c^{A} c^{A$

I would like to acknowledge my debt to, in alphabetical order, the experts:

• Prof Paul Bowen, Neil Cunningham, Seth Lindberg, Roelof Luth, Dr Hans-Martin Sauer, Dr Saeid Savarmand.

They have each helped me considerably, though I stress that all opinions and errors in the Guide are my own.

It was an automotive engineer from Germany, Sebastian Abbott, who mentioned how "Maybe we should check out the rheology of the system" seemed to induce panic. Rheology should be a routine methodology for those who need it as part of their day job, just as they need other measurements, such as spectra, in which they do not have to be great experts. It should not be a source of alarm. That quote was the inspiration for putting this guide together. The act of writing it has reduced my own sense of panic and alarm. I hope that it will do the same ${}^{[i^{(i)}]_{i}} = \frac{1}{2} \left[\frac{1}{2} \left[$

Steven Abbott, Ipswich, 2018

1 Setting the scene

What problems are we trying to solve?

 $\begin{array}{l} (E \mid a \in \mathbb{Q}^{1} \\ a \in \mathbb{Q}^{1} \\ (a \in \mathbb{Q}^{1} \\ a \in \mathbb{Q}^{1} \\ (a \in \mathbb{Q}^{1} \\ a \in \mathbb{Q}^{1} \\ (a \in \mathbb{Q}^{1} \\ a \in \mathbb{$

 $Ü@^[[!^^ *[c[c[æ àæå •cæ:c-[: {^ c@æ}\• c[c_ [ÎE]^cc^: _ [!å• _ @i&@ i}] normal English mean the same and which start with the same 3 letters: stress and strain. As we cannot make the words go away we have to learn not to get confused.$

- Stress is a force per unit area applied to an object. Because force is in Newtons, stress is N/m² or Pa.
- Strain is the % increase in length of an object when it is stressed; i.e. it is increase of length divided by the original length. It is a pure number, without units.

You can't get a strain without a stress and you don't have a stress without a strain. Rheologists seem to outsiders to make random decisions about the

As we shall see, most materials have a mixture of elastic and viscous properties so we need that equation later. For now we want to focus on viscosity, where I $\hat{a} = \hat{a} = \hat$

For viscosity, strain is not useful because viscosity appears only when motion is involved. That is why we need strain *rate* $\hat{E}_{0ik} = 0 = 0 = 0$, i = 0 = 0, i =

Let us see how the idea of viscosity, strain rate and the required stress are interrelated. The equation also tells us that viscosity must have the units of stress/shear_rate, which is Pa/(1/s) giving us our viscosity unit of Pa.s. A viscosity of 1 Pa.s is quite high, so for convenience, lower viscosities are usually cited as cP, where 1 cP=1 mPa.s. It is annoying that we have P for Poise and Pa.s for Pascal seconds and many of us have messed up by mis-reading the unit and therefore being out by a factor of 10. So, look out for P (which is 0.1 Pa.s) and Pa.s and don't feel too bad if you occasionally get them confused.

And while we are talking about confusion we also have the rheology world \tilde{e}_{a}^{*} and $\tilde{e}_{a}^{*} = cae^{1/3} + cae^{$

c[&[}c! [| c@^å!] ![å ~ &cÈ Y ic@ { [å^•c^ [!c c@^^ &[~]å @æç^ ~[~]å , @^c@^! c@^ viscosity was shear thinning (which would have helped) and how the viscosity changed with % solids. It turned out that, as is frequently the case, the solids had been pushed to a practical limit and that a small increase (via evaporation [} c@^ { æ&@i}^) |^æå• c[æ •i* }i, &æ ci}&!^æ•^i} çi•&[•ic^ , @i&@ i} c'! } &[~]å create the coating defects I was there to troubleshoot. The common fact that æ • { æ|| &@æ} *^i}][[^ { ^! &[}&^ c!æci[} &æ } { æ\^ æ |æ!*^ åi ^!^} &c [c@^ viscosity is discussed later.

V@^, $|\cdot c \approx a c i & h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h c | h$

2 Shear-rate dependent viscosity

What problems are we trying to solve? Õåçå}* [`¦ '`åå æ •å}*|^ "çå•&[•åc^" `•`æ||^ å• }[c *[[å ^}[`*@Ê •[_^ }^ å• }[c

you are in terms of shear rate and, therefore, viscosity. I like to use a simple adhesive as an example.

The user opens the cap of the tube and wants to squeeze out the adhesive. You $a[]'c \ x \in c^{a} \ c^$

This sort of quick analysis on your own formulation is very powerful. It combines your knowledge of how the formulation *should* behave with how it *will* behave (as judged by the Cross model and your estimates of shear rate). If your rough estimates tell you that each process is comfortably in the right domain, then no further work is required. If they tell you that one part of the process is problematic, then you have more work to do. If your estimate of shear rate tells $[\circ @@c c@i]^* \bullet @!^ a[!a^!]i^\circ c@^ o[` }^{a} c[!^, }^ c[` !^ \bullet ci { @c^ i} @ \bullet [{^$ ${ [!^ ^c] !^i { ^c} ! i { ^c} !$

2.1.2 What causes shear thinning?

We start with a discussion of shear thinning in *polymeric* systems which is important in its own right and leads us onto a key theme that deserves our attention because we should be spending more of our rheological time trying to understand it. The shear thinning of *particle* systems does not happen below $\mathfrak{a} \cdot]^{\delta_i}, \mathfrak{c}_{[]} \{ \land : \mathfrak{a} \cdot \mathfrak{a} \cdot \mathfrak{a} \cdot \mathfrak{c}_{[]} \} : \mathfrak{a} \cdot \mathfrak{$



We have our streamlines. At low shear values, a polymer in the liquid spans a number of streamlines. Those in the fast stream are being held back by those in the slow stream, so there is a general $i\}$ i^{+} i^{-} $i^$

complex. The ability for a polymer to tangle depends on its concentration (of course), on its MWt³ (bigger MWt will tangle more, of course). It also depends on how "entangleable" the polymer is which is more puzzling. For some polymers, a low MWt is enough to tangle, for others it needs a large MWt. If we know the "critical entanglement MWt" then we can predict the low shear viscosity.

Entanglement is important across large areas of formulation space. It is what gives us strong adhesion, it gives us strength and toughness, and it is what (often) stops us from adding as much polymer as we might like because the formulation gets too viscous to handle. For many formulated products and systems, entanglement is good, yet it is entanglement which makes it hard for us to formulate them.

Given that polymers have a critical entanglement MWt, M_c , we should all know their values so we can work out whether we want to be below or above it. The problem is that although values are known for a handful of simple polymers, they are unknown for most of the real-world polymers we tend to use. Until suppliers get into the habit of providing M_c values, we should get into the habit of estimating them ourselves. Two apps help you to do this.

³ It gets tedious to keep typing molecular weight, so I use MWt.

App 2-2 <u>https://www.stevenabbott.co.uk/practical-rheology/Low-Shear-Polymers.php</u>

App 2-3 https://www.stevenabbott.co.uk/practical-solubility/polymer-viscosity.php

This app takes in M_c as a parameter and includes a measure of solvent-polymer &[{]æɑiài|ic^Ê c@^]æ!æ { ^c^! , @i&@ * [^• ~![{ $\in (c[cæ||^ &[{]æcià|^Ê][|^ { ^! filly expanded}) to 0.5 (the polymer is bordering on unhappy). You can read the detailed text of the app to learn more. The point is that although polymer viscosity behaviour is more complicated than we would like it to be, it$ *is*possible

Арр 2-4 _____

some sort of measure, though it is arguably better as the "relative area" obtained by dividing by the area under the up curve.

Out of personal interest, I wrote an app that describes an oscillatory method, giving the G' value with time after stopping a fast shear.

Equ. 2-7
$$G'_{t} = G'_{0} + A t^{n}$$

I do not see how it can be of much use because it just gives a power law, n, for $c@^{ci} \{ \ e^{a} \$

With hindsight I can see that my ignorance of entanglement was behind my puzzlement. I had never heard of critical entanglement MWt and how it varies $a_i^{a_i}a_i^$

I then "discovered" associative thickeners. These were a revelation because $(\mathbb{Q}^{1})^{1} + \mathbb{Q}^{1} = \mathbb{Q}^{1} + \mathbb{Q}^{1} = \mathbb{Q}^{1} + \mathbb{Q}$

All this is obvious with the right language of timescales and entanglement and rather obscure without it.

The implications for the formulator are clear. If you need an entangled system for other purposes (such as adhesion), don't expect fast relaxation times and low thixotropy. Because the amount of entanglement is concentration-dependent, expect thixotropy to change dramatically over a relatively small range around a critical concentration.

If you require viscosity coupled with low thixotropy, then associative or particle $c@i\&\^}^{\bullet} \otimes a \circ ac|^c^{\circ} \circ ac|^c^{\circ} \otimes a \circ ac|^c^{\circ} \circ a \circ ac|^c^{\circ} \circ a \circ ac|^c^{\circ} \circ ac|^c^{\circ} \circ a \circ ac|^c^{\circ} \circ ac|$

App 2-6 https://www.stevenabbott.co.uk/practical-coatings/distances.php

The app shows the average distance, d, between particles as a function of $\c\%$ [~]a:ci&] $^{\bullet}$ V@ $^{i}ac^{-i}$ [$\&\&^{i}$]aci[$\c\%$] $\c\%$ [$\c\%$] a^{-i}] $^{\circ}$ [$\c\%$] $\c\%$] \c\%] $\c\%$] \c\%] $\c\%$] $\c\%$] $\c\%$] $\c\%$] \c\%] $\c\%$] $\c\%$] \c\%] $\c\%$] $\c\%$] \c\%] $\c\%$] \c\%] $\c\%$] \c\%] $\c\%$] \c\%] $\c\%$] \c\%] \c\%] \c\%] $\c\%$] \c\%] \c\%]

spheres, d is, on average, large, so it will take a long time for them to travel the

[$\hat{a}^{a} + \hat{a}^{b} + \hat{a}^{b} + \hat{a}^{a} + \hat{a}^{a} + \hat{a}^{b} + \hat{a}^{a} + \hat{a}^{a}$

Fortunately a wonderful paper⁵ from Daniel Bonn's group at U Amsterdam $a^{a} \cdot a^{ia} \cdot$ Q} $a_{n}^{(1)} a_{n}^{(1)} a$

The second method (bottom left) takes the same experiment but somehow ^¢c!æ&c• æ çã•&[•ãc^ ~![{ c@^ åæcæ æ}å]|[c• c@æc æ*æã}•c È Q &[}-^•• c[}[c knowing how this is done, so the values in the app are plausible (I checked with some papers) without being calculated. Maybe it is so obvious how to extract c@æc c@^ æ`c@[!• ååå }[c @æç^ c[^¢]|æã}È Q jã|| @æ]]ã|^ `]åæc^ c@^ æ]] æ}å c@ã• paragraph if someone would enlighten me.

The next technique provides three ways of extracting a value from the data. The basic experiment to measure G' and G'' will be described in the Semi-Solids chapter but hopefully readers are at least aware that these are standard values obtained from oscillatory rheology. The stress is steadily increased (so the best machine is a controlled stress machine rather than controlled strain) until there is an obvious change in the measured parameters. Now we can extract the values $a^{-1} = a^{-1} a^$

- Very popular, because it is simple for humans and computers to spot it, i • c[cæ\^ œc c@^ &¦ [••Ë[ç^\] [i]c , @^} Õ'' à^&[{ ^• |æ|*^\ c@æ} Õ'Ê iÈ^È the system becomes more viscous than elastic. This value is usually an overestimate and is sometimes called the Flow stress rather than yield stress.
- 2. T [!^ c! `^ c[__y is to identify when the G' value starts to decrease which, by a^, } ici [}Ê { ^æ} c@æc ic' cæ !ci} * c[|[•^ ic• ^|æ•ci& }æc `!^È V@i• i• c!i&\^ c[a[by computer and rather obvious by the human eye.
- 3. Because rheologists love to plot data in other manners, the complex strain, 'É ã• &æ|& `|æc^å æ• Ùc¦^••ÐT [å`|`•Ê äÈ^È ĐÕ' , @^¦^ Õ' ã• c@^ &[{]|^¢ { [å`|`• *ãç^} à Õ' MÕ' ÉÕ'' È @ ã• •æåå c@æc ^[` &æ} •^^ , from intersection of the two relatively straight lines.

Next (top right), you set up a (very) small shear rate and watch how stress grows with strain. The yield stress is the plateau value where the strain just keeps going.

Finally (bottom right), you can do a set of creep experiments where you set a $, c^{a} \cdot c^{i} \cdot e^{a} \cdot e^{a$

Whether you measure yield stress or strain depends on what question you are trying to answer.

3.2 Using yield stress or strain values

For many formulators, yield stress is a non-issue and this chapter can largely be ignored. For some, it is a vital parameter for a product such as the hand creams $[\frac{1}{2} - \frac{1}{2} \cdot \frac{1}{2} \cdot$

 $V@^{\bullet}\&i^{k} = [-] |^{a}i\&ci | c| ||i| + i^{i}|a| + c|^{\bullet} i^{\bullet} a |c| + i^{\bullet} a |c|$

- Ensuring that your measurement really relates to the end product performance. This often involves consumer test panels who poke, rub, lick or [c@^!,i•^i}c^!æ&c,ic@ æ !æ}*^ [~åi ^!^}c~[!{`|æci[}• æ}å •æ^, @i&@ c@^^ prefer. With luck you can relate that to an objective measure of yield stress.
- 2. Ensuring that your objective measure of yield stress is comparable between labs, between operators and between samples - in other words that it has a reasonable Gauge R&R⁶, showing that the noise in the measurement is less than the signal. Trying to hit a target of 43 Pa when measurements vary randomly between 30 and 60 is not a great way to formulate.

⁶ Gauge Repeatability and Reproducibility - found in any reputable process control statistics package. It is amazing, and depressing, how many "industry standard" tests fail elementary Gauge R&R analyses and are, c@^\^_[\^E``},c~[\^E``},c~[\`]`\][•^E

4 Semi-Solids

What problems are we trying to solve?

Many of our formulations are neither pure solids nor pure liquids. So we need to be able to understand how much they are of one or the other. A straightforward measurement of G' and G'' will do this for you. But it is missing a key point. *Everything* is a solid at a low-enough temperature or a short-enough timescale and *everything* is a liquid at a high-enough temperature or a long-enough timescale.

 $\acute{O}^{\&} \bullet^{\circ} \{ [\bullet c \sim [| \{ | aci [\} \bullet @ acc \circ c [] ^ | ~ [| \{ | \} a^ | ai ^ | ^] c ci \{ ^ \bullet \& a | ^ \bullet (^ t * t a pressure sensitive adhesive must stick quickly yet not creep over long times), we need to be able to both measure$ *how*things change over temperature and time, and understand*why*they change so we can formulate intelligently.

There are no such things as solids. At a high-enough temperature (obvious) $[\frac{1}{2} \times \frac{1}{2$

We therefore end up with the Deborah number $De = t_{relax}/t_{observed}$, i.e. the ratio of the time over which the system relaxes to the time over which the system is observed. When De is large, the object is a solid, when it is small, the object is a liquid. Water observed on a picosecond timescale is a formidable solid⁹ and a mountain on a billion year timescale is a liquid. Reduce the temperature and water becomes a solid with a glacial relaxation time, and at high temperatures a mountain becomes lava which can be a liquid even at a ms timescale, though chemistry and temperature may require measurements on timescales of seconds, minutes or hours¹⁰.

If, at normal temperatures and timescales we have a liquid, our default is to measure its viscosity. If we have a solid, our default is to do tensile testing for its modulus. If you are reading this guide then you probably have a semi-solid

⁹ There are many stories about the lab in Wales that measured the high-speed properties of water, using a gun $c[, \dot{a}] = \frac{1}{2} \frac{$

¹⁰ Those lavas that seem not to be moving but over a couple of days can spread over a small village.

with a mixture of properties that will vary strongly with temperature and with timescale.

The classic way to get at this mixture of properties is via G' and G". As these are easily described, we can spend most of this chapter discussing why other ways of looking at the properties of semi-solids should be a normal part of our rheology repertoire and of ways of thinking about materials in general.

4.1 G', G" and tan

The mixture of fear and ignorance about G' and G" is unnecessary and unfortunate. They are simple to understand and are powerful indicators of key aspects of many formulations. Most of us are happy with E, the tensile modulus, which is simply stress/strain, where the strain is *along* the material sample. G is the shear modulus, stress/strain, with the strain being *across* the material. So there is nothing mysterious about G values in general. The reason we have G' and G" is that we need to describe the stress response to the strain (or strain response to the stress, which gives us equivalent terms J' and J" discussed later) in terms of a purely elastic term, i.e. as if it were a pure solid, and a purely plastic (or viscous) term as if it were a pure liquid. We can best describe how this comes about with an app:

App 4-1 <u>https://www.stevenabbott.co.uk/practical-rheology/G-Values.php</u>

We have the sample squeezed between two plates, one of which can oscillate. We might oscillate it with a known maximum stress or maximum strain, creating a stimulus. We measure the response either as a stress on the lower plate (for oscillating strain) or as a rotational speed (strain rate) on the plate to which a known stress is applied. These are, respectively, the controlled strain and controlled stress rheometers, with endless discussions about which is better or better value for money. $\emptyset[\ |\ c@^{\circ} \{\ xe^{\circ} |\ \{\ xe^{\circ} |\ xe^{$

In the image above, the stimulus creates a response of amplitude 0.5 (again, we don't care about the number or units at this stage). The important point is that $c@^{+} = [] + c@^{+} = c@^{+}$

Armed with this straightforward information you can now tell at a glance from a typical oscillatory rheometry plot how the system behaves as parameters (such $a \cdot c^{1} = 1^{1}ac^{1} a \cdot e^{-1}ac^{1} a + e^{-1$

When, for example, the G' line dips below G", that is an indication of a significant change. We have seen this in one form of yield stress measurements. For classic polymers the temperature at which this happens is the glass transition temperature, Tg. When you find the conditions on the graph that apply to your formulation you will know whether it is mostly elastic or mostly viscous.

4.1.1 Storage and Loss

So far I have described G' as elastic and G" as viscous. I could also call G" plastic, which allows us to talk about the "elastic and plastic" components. $\dot{U}|_{aecia} = \frac{1}{2} |a| |a| + a^{+} + a^{+}$

The other common terms are "storage" for elastic and "loss" for viscous. A purely elastic material stores the energy under strain and returns 100% of it on release. A purely lossy, viscous material has no recovery after being strained and all the energy has been lost as heat.

You can feel free to choose whichever pair of terms pleases you; you just need $c[a^{*}, a^{*}, c@ac [c@^{+}, {a^{*}, @c &@[[•^ & a^{*}, ^{+}]c]aa!b}]$

There is, however, a catch. To say that your formulation is "mostly elastic" or "mostly viscous" is true only for a specific set of conditions. Your formulation is likely to pass through a wide range of conditions so you need to know how the relative elastic and viscous proportions will change. For that we need to return to the Deborah number.

4.2 TTE/TTS/WLF

whichever way you prefer to think about it. Similarly, at normal frequencies, water has a respectable G' below 0°C and rock has a nice G'' above 1000°C, so we have a temperature dependence as well.

Returning to reality, in a typical rheometer we can measure only a narrow range of frequency and temperature. Let us say that our specific rheometer can only cover 0.01 to 10Hz and -10 to 80°C. Fortunately, we can create measured values over a much larger *virtual* range. For example, a measurement made at 0.01Hz at 80°C might be like a measurement made at 0.0001Hz at room temperature. Think about it; at high temperatures things flow and at low frequencies things flow, so the 80°C measurement is rather like a very slow measurement at room temperature. Going in the other direction, a measurement at -10°C and 10Hz might be like a measurement at 100Hz at room temperature, because things are more rigid at low temperature and at high frequency. So our limited rheometer can now, effectively, measure from 0.0001 to 100Hz.

The fact that time is equivalent to temperature or that you can superimpose time-related data with temperature-related data is well-established across a remarkable range of practical materials and you can generally assume that it applies to your specific formulation. We therefore invoke TTE (Time Temperature Equivalence) or, according to local preferences, TTS (Time Temperature Superposition). If you want to appear super-smart you can call these tTE and tTS because time is usually a small t and temperature is usually a large T. To do

App 4-2 <u>https://www.stevenabbott.co.uk/practical-rheology/WLF.php</u>

The data on the left aren't rheology data, though they could be - WLF is a universal phenomenon. They happen to be a set of adhesion peel energy curves versus the rate, R, of measurement done from -80 to 80°C. At high temperatures the adhesion is low because the polymer is soft, at low temperatures it is high because the polymer is rigid. Adhesion increases with peel speed. So we have $\hat{I} \&^{+}c^{+}$, $\hat{e}i\&@ \&!^{+}c^{+}$, $\hat{i}i\&^{+}\hat{E} a^{+}c@\&!a^{+}c[,ci]c[æ ài*]i\&c^{+}c[- ,@æcie * [i] * []E By knowing that in this case <math>T_r = -80$ °C and by playing with the C_1 and C_2 sliders $\hat{i}cie^{-}][eeia]^{+}c[\&!^{+}æc^{+}æ ei]^{+} |^{+}YŠØ \&^{+}c^{+}\hat{c} @^{+}c@^{+}\&[][^{+}e[-c@^{+}ai^{+}c]^{+}c]$ portions (which can overlap) relate to the colours in the original graph.

The WLF curve tells us what the peel would be at -80°C at a rate of 10⁻¹⁴ m/s. And that is a nice give-away. You often see impressive G':G'' plots spanning a vast frequency range and you can imagine that they must have an amazingly good rheometer - until you think about the timescale on the graph.tualo3FEFF0020**>**BDC

ÜŚŚadÒpsYcsYdCV secondsrsas whrdd tha yearLW7q–bpLW%aAi0LW"a–b-™®tŷjê7ers

I had been talking to a team working on a pressure sensitive adhesive, PSA. I had pointed out in theoretical discussions how the WLF version of the results would help understand the adhesive properties.

Q

If we all had full plots such as these for our formulations we would know how they behaved with sudden shocks (high frequency) or over large timescales, or low or high temperatures. These plots are a super-compact way of providing answers to a lot of questions - within the limits of the assumption behind the measurement which is of small strains.

For those who remain cynical about all this and regard WLF plots as some sort of physicist's game unrelated to reality, I have one more thing to say about PSA. You can create Burgers-style G':G" plots via WLF. But what do they have to do with the important issue which is the adhesion of the PSA? The answer is "a lot". You can measure the same PSA's adhesion over a large range of temperatures $a^{a}_{a} ci \{ ^{\bullet} a \}^{a} a \{ ^{a}_{m} c^{a}_{m} \bullet i \}^{*} |^{A}]| [c cia YŠR Y@^{A} ^{[*a}_{m} a [\bullet [É^{[*a}_{m}] ,]^{a}_{m} c@ac c@^{A}_{m} three parameters, C_{1}, C_{2} and T_{1} are identical for the rheology and adhesion$ datasets. So at a very fundamental level, adhesion, WLF and the Burgers modelare inter-related.

4.3.1 Your own G':G", WLF insights

You may recall the idea from an earlier chapter of becoming a superstar by being able to do rough calculations of shear rates and, therefore, knowing what $^[i]_i \dot{c}_i \cdot \&[\dot{c}_i \cdot \&[\dot$

What are the timescales of PSA processes? The key process of sticking has to be around 1/s, you need it to stick "immediately". Now imagine peeling a piece of adhesive tape for an adhesion tape test at 1 cm/s. The thickness of the adhesive is (in round numbers) 0.01 cm, so we are ripping it apart at 1/0.01 ~ 100 /s. If we apply a weight to the tape so that it is being sheared, we are worried about velocities of 10 cm/day, or around 10⁻⁴ cm/s, giving us 10₋₄/0.01 ~ 0.01 /s.

This rough analysis tells us that at the very least we should understand the G':G" behaviour over a 0.01 to 100 /s timescale. A large G" at the 0.01 /s timescale would be as catastrophic (easy shear) as a small G' at the 100 /s $ci \{ 4 + 8a| (i) + 2a| + 2a|$

As has been shown many times in the PSA world, getting the right G':G" at all three timescales does *not* guarantee success - PSAs are far too complex. On the other hand, having any of those three wrong *does* guarantee failure.

Q &æ} c@^¦^~[¦^ •æ^ ,āc@ &^¦cæã}c^ c@æc ã~ ^[˘¦]¦[å˘&c @æ• c[]^¦~[¦ { æc åã ^¦^}c cã { ^•&æ|^• (æ}å ~^,]¦[å˘&c• å[}'c)Ê ^[˘ ,ã|| *æã} æ |æ¦*^ à^}^,c ~¦[{ æ ˘ ĩ&\ analysis of what those timescales will be and what general G':G" values are needed. By meeting those general requirements, success is *not* guaranteed; failing to meet them *is* guaranteed to render your formulation sub-optimal.

It is highly likely that to get the values at all relevant timescales will require some WLF work. Trust me; if I can do it with zero notice late at night with no app to help me, you will have no problem doing it if you can create the quality time away from daily pressures of formulation to become comfortable with a WLF analysis of your own system. Your rheometer probably has some presets that \vec{a}

5 Interconversions

What problems are we trying to solve?

Ù^ { $i\ddot{E} \cdot [|i\mathring{a} \cdot \&\mathscr{B} \rangle \mathring{a} [{\mathscr{B}^{\circ} \circ @i}^{*} \cdot \cdot \&@ \mathscr{B} \cdot [, \mathring{E} \&!^{]} \mathscr{B} \mathring{a} !^{|\mathscr{B}} \mathscr{C} V@^{, ! \circ c}$ problem is that if you think of each behaviour as something separate (e.g. you $\mathring{a} [\tilde{O}'K\tilde{O}'' { ^{\mathscr{B}} \cdot !^{ } {^{\circ}} \mathscr{B} \mathring{a} [} \mathscr{B} \mathring{a} \land !^{ } c { \mathscr{B}} @i}^{?} \mathring{E} \&!^{ }] { ^{\mathscr{B}} \cdot !^{ } {^{\circ}} {^{\circ}} }$ you are missing out on a lot of information. The more important problem is that each type of measurement has a natural, convenient timescale so it might not be possible to get, with one technique, the data you want concerning a timescale that is important in your formulations.

It turns out that all these behaviours are mathematically equivalent so, in principle, a measurement of, say, creep over one timescale, can tell you about G':G" behaviour in cases where that timescale is not readily accessible. It also turns out that we can get a grand view of these processes via "spectra" with respect to time. We therefore have the potential to combine and interconvert our separate measurements into whichever views provide us with the fullest insights into our formulation challenges.

Everyone, except me, knew that it was possible to convert between rheological measurements. Once I had found this out for myself I read many papers saying why interconversion method A is no good and how method B is better, without $a\&c^*a||^{c}||_{a}^{b} + (a||_{c}) = (a||a||_{c}) + (a||a||a||_{c}) + (a||a||_{c}) + (a|$

I do not have the brain power or mathematical training to do the job that the specialist academics should have done. But at least I have made an interconversion app that shows the possibilities and discusses the principles. My own grasp of the key inter-related concepts in rheology has improved greatly during the creation of the app and my aim in this chapter is to persuade you $\[(a^{(a)} - [(a^{(a)} - (a^{(a)})])] (a^{(a)} - (a^{(a)})] (a^{(a)} - (a^{(a)})] (a^{(a)}) ($

First we must understand about relaxation and creep.

5.1 Relaxation and creep

Y@^} ^[`æ]]|^æ•`åå^}É,¢^å•clæi}c[æ sample it will start to relax and the measured stress will decrease. The image shows a c^]i&æ|]|[c[~•cl^•• [ç^l ci { ^È Q- c@^ i}iciæ] strain had been doubled, the initial stress would also have been doubled. So you also see equivalent plots of Relaxation Modulus $\widetilde{O}M \quad \theta \cdot clæi\} \doteq U \ &@]|[c \cdot æl^ U^|æ¢æci[] & lç^•Ė$

Q~ ^ [~ æ]]|^ æ, ¢^å •cl^•• c[æ •æ {]|^É ǎc , ǎ|| suddenly start to creep, i.e. the strain increases. The image shows a typical plot of •clæå} (@^l^ •@[, } æ• ~[l @å•c[lå&æ| l^æ•[}•) over time. If the initial stress had been doubled the resulting strains would double. So you also see equivalent plots of Compliance RM•clæå}Đ Ė Ù ~&@]|[c• æl^ Ô[{]|åæ}&^ & iç^•Ė

Relaxation is typically modelled using a Maxwell model:

Equ. 5-1
$$\frac{\delta \gamma}{\delta t} = \frac{\sigma}{\eta} + \frac{1}{E} \frac{\delta \sigma}{\delta t}$$

What this tells us is that the rate of change of stress with time (which is what interests us) depends on the modulus (here we use the tensile modulus E but this could equally be the shear modulus G) and on the ratio of the current stress $c[c@^{*}ci \cdot \&[\cdot ic^{*}] + [a^{*}]^{*}] = [a^{*}]^{*} = [a^{*}]^{*$

Creep is typically shown via the Kelvin-Voigt model:

Equ. 5-2
$$\frac{\delta \gamma}{\delta t} = \frac{1}{\eta} (\sigma - E\gamma)$$

As with Maxwell, we are interested in the response to a sudden increase to a &[$\} \circ c \approx \$

App 5-1 https://www.stevenabbott.co.uk/practical-rheology/Relaxation-Creep.php

We can now play with the various stresses and strains, timescales and spring and dashpot parameters. Because such experiments are carried out on $|^{exic}|^{ 'ia} { ac^{ia}| \cdot \cdot i}^{ 'ia} { ac^{ia}| \cdot \cdot i}^{ 'ia} |[\cdot \cdot i^{+} \cdot \cdot \cdot i] c@^{ 'ua} |a|^{ *^{a}} a [] \cdot ^{ ia} { ic} |ia|^{ *^{a}}$ with stresses in the MPa range, you can choose the units - these merely change the graph labels.

As mentioned at the start of the book, I am being inconsistent: strains are shown as rather than . In this sort of plot it would be odd to use . As I said at the start, rheology is full of inconsistent units.

The curious shape of the curves comes because after 150s (see the t_{stop} slider) the strain or stress is reduced to zero and the system starts to return to its original value via its elastic response though clearly it will never fully return because the viscous component is irreversible. After 50s, (t_{hold}) the stress is reapplied and the strain or stress increases further. Such experiments are very much part of the repertoire of relaxation and creep measurements, though I currently have no idea how you use the data from multiple starts and stops.

Earlier I said that all real-world relaxation and compliance curves can be $a^{A} = a^{A} = a$

 What happens when linearity of response breaks down is discussed in a very brief chapter.

These two plots are based on elastic and viscous components. So they must be related somehow to G' and G". The timescales in the screenshot are in the 100s range, so 0.01HZ. A typical oscillatory measurement of G' and G" takes place in the 0.01 to 10Hz range, So these data should have some links to low frequency values. If we did a much slower creep test (and why not?) maybe we could get G':G" data in the super-low frequency range. If we wished to know about relaxation and creep behaviour in the 0.1s timescale (which is tricky because $c@^{2} @^{2} @^{2} @^{2} (c[b) & ca^{2}) ^{4} @[abave colored abave colored colored colored abave colored abave colored color$

5.2 The power of interconversions

If we had such a plot of "interest" versus frequency we could then think through the timescales of the processes that are important to our formulation and know $\hat{a} = \hat{a} + \hat$

The plot of H (representing the degree of interest) versus t is called the *relaxation spectrum*. I hope, therefore, that you will take the trouble to learn about H (and its equivalent in terms of creep is the compliance spectrum, L), \mathfrak{B} , \mathfrak{B} , \mathfrak{B} [$\mathfrak{C} \mathfrak{B}$ [$\mathfrak{C} \mathfrak{B}$], $\mathfrak{C} \mathfrak{B}$], \mathfrak

Before looking at relaxation spectra we need to think more about creep-style measurements. The compliance curve, the creep strain experiment normalised $\hat{a} c^{0} \approx]$ | $\hat{a} \cdot \hat{c} \approx \hat{c}$

able to assemble a good-enough collection of algorithms by combining Ferry, Tschoegl and Park.¹³

App 5-2 https://www.stevenabbott.co.uk/practical-rheology/Interconversions.php

What the screen shot doesn't show is the rather messy method for creating the \hat{a}] $\tilde{c} \cdot \ddot{E} \approx \cdot \hat{a} \cdot \hat{c}$ [~ $\tilde{O}($)

Because compliance is, at heart, just 1/relaxation, it is not surprising that the curves look somewhat like mirror images. If it were that simple then life would be much easier. In fact the conversions are not at all straightforward and the curves, at the detail level, are not mirror images.

Some of the curves have calculation artefacts. That is partly a limitation of the algorithms I used and also a characteristic of the problem of these conversions. I have the advantage of data from Ferry, covering many orders of magnitude of timescale, which makes it possible to show the full conversion capabilities. In real life you will have only a limited set of data unless you do extensive WLF conversions. The fewer the number of datapoints, the more likely the conversions will contain artefacts. As many papers stress, some of these conversions are "ill-posed problems" which means that there is no unique solution.

Out of personal interest I attempted to create the interconversions for the Burgers model shown in the previous chapter and discussed further below. You can judge my attempt by selecting the option from the combo box. Although I &æ} &[}c^ic ~![{ $a \cdot ia^{ia^{-1}} [\tilde{O}() cal^{ia^{-1}} [\tilde{O}() c$

 $V@^{ai} & [ci^{-i}c^{i}c^{-i}] \\ \{i^{*}@c \\ \{\infty^{i}c^{-i}c^$

 $|^{\infty}|_{\tilde{a}} \bullet \hat{a}$ Â

why interconversion is so important, simply because I know a lot about them and already have a good model for what they should be like. If I had more experience in other areas I could equally have used them as examples because the principles are general. Macosko's *Rheology Principles* book is especially good for those who want to explore other implications of entanglement.

The common idea of a strong adhesive (such as an epoxy) is that it gets its strength from having a high elastic modulus. A polymer with lots of entanglement (such as a cross-linked epoxy) will behave as a pure G' over the normal timescales that we typically measure. Such a polymer would make a useless PSA because these have to be soft and accommodating to the surface - they must have a G' no larger than 0.3MPa, compared to a typical epoxy's 4GPa.

Any polymer without entanglement is going to behave with a large G'' element as there is nothing much to stop the polymer chains from sliding past each other. A PSA without tangles might still achieve the 0.3MPa G', while having a $\tilde{O}'' \bullet i^* i_{\delta} \& B c \circ i_{\delta} \oplus A c \circ i_{\delta} \otimes i_{\delta} \circ i_{\delta$

Figure 5-1 The Burgers Viscoelastic model for a PSA fully interconverted

What I especially like about this interconversion is the ability to think better about creep behaviour. It is rather easy to design an excellent PSA which fails in the application because of creep. The standard "creep" test is simply "how long does it take for this sample to fall from the test rig", providing very little information about what is going on. The interconverted creep curves allow me to think more about the timescales over which creep will be a liability. If the PSA world routinely looked at creep this way, it would be much more knowledgeable than it currently is.

5.4 M_c from Likhtman-McLeish theory

Suppose you have a full G', G'' curve covering many orders of magnitude. There is one more thing you can do with it - work out the critical entanglement molecular weight M_c. The theory was developed by Likhtman and McLeish¹⁵ some years ago, but most of us were totally unaware of it because it's the sort of thing known in the specialist M_c community, not among those of us who need $ic\dot{t} \oplus a$] $]\dot{a}$, $\dot{a} c^{+} \cdot \dot{a}$ [$\dot{t} \pm https://www.stevenabbott.co.uk/practical-rheology/L-M$ Mc.php, was made possible by the kind assistance (acknowledged on the apppage) of those who are supporting and developing this, and other theories forthe future. Indeed, they have provided L-M theory as part of the impressive<math>idit = ab i = ab i

Figure 5-2 The Likhtman-McLeish route to fnding M_c values.

The app is mentioned here because L-M theory provides us with two key outputs - the $M_c i \circ |-\infty|^2 \otimes a \otimes U[\circ |+| \otimes e \otimes i] \circ |+| \otimes e \otimes i |+| \otimes i |+$

The paper itself isn't so hard to read and the formulae not so hard to understand. Unfortunately one of the formulae is near-impossible to calculate. So in the app I make use of (as does RepTate) some heroic pre-calculations of curves depending on all (relevant) possible input values. The app, therefore, is not doing any calculations, just showing the curves expected from the current parameters. This means that we have a very powerful app without the need for vast computational power.

Q- (ài* à-) [@æç^ æ] [] { { } ; ic@ æ [[]] [] ^ åi•] ^ !•ic^ i} å^¢ (ŁFĖF) æ}å à- (ài* à-) [@æç^ æ -] YŠØ •^c [- Õ'KÕ'' åæcæ c@^} c@^ ,cci}* i• ^æ• æ}å i- (ài* i-) [have the WLF data corrected for a temperature that is a reasonable balance between T_g and T_m the results are sound. Most of us, most of the time, have polydisperse polymers so what should we do? The purist answer is to wait till some newer, better theories are available (and added to RepTate). My answer is to be pragmatic and get at least a working idea of what's going on with your polymer via a pragmatic M_c.

5.5 Impossible interconversions?

The book started in the familiar world of rotational viscosity, where we can go $-\left[\left\{ \begin{array}{c} 0 & 0 \\ 0$

I will say no more about extensional viscosity other than to express my regret that a technique which should be so relevant to so many formulation issues $\{x \in x\} = \sum_{k=1}^{\infty} \{x \in x\} = \sum_{k=1}^{\infty} \{x \in x\} = \sum_{k=1}^{\infty} \|x\|^{2} + \|x\|^{2} = \|x\|^{2} + \|x\|^$

I am genuinely astonished that after decades of rheological studies, there is (apparently) no methodology for combining rotational and oscillatory rheology. Readers will say "What about the Cox-Merz rule?" The answer is that it is not a rule and if it applies at all it is to a rather narrow domain (and does *not* apply at all to particle systems¹⁷)È $\hat{O}[\phi E T^{+}: \cdot a^{\circ} \cdot c@ac c@^{\circ} ca^{\circ} \&[-ac^{\circ}E - Eac a * ac^{\circ}] \cdot @^{\circ}ac^{\circ} @^{\circ}ac^{\circ}ac^{\circ} @^{\circ}ac^{\circ} @^{\circ}ac^{\circ} @^{\circ}ac^{\circ} @^{\circ}ac^{\circ} @^{\circ}a$

¹⁶ Christopher J.S. Petrie, *Extensional viscosity: A critical discussion*, J. Non-Newtonian Fluid Mech., 2006, 137, 15–23

¹⁷ For those who are comfortable with "shear stress equivalent inner shear rate", Cox-Merz can be applied to particulate systems. I confess to not having the slightest idea what that phrase means. Those who are interested &æ}, }å c@^ iå^æ• i} c@^ _ [{\ [- Ú|[- Õ|^i••|^ i} Sæ!]•]`@^È

5.6 What can we do with interconversions?

This means that the current answer to the question of what to do with interconversions is "not much".

If I were a rheologist I would see this as the grandest of grand challenges. Whoever could bring all those things together into a workable tool would transform our ability to better understand our systems via a series of systematic measurements.

So despite being at times rather critical of rheologists, I shall end this chapter [$\c@ac$][\bullet iciç^ $\c@ac$][\bullet iciç^ $\c@ac$][\bullet iciç^ $\c@ac$][\bullet iciç^ $\c@ac$][\bullet ici,^å $\c@ac$][\bullet iciç^ $\c@ac$]] \cal{ac} (\cal{ac}) [\cal{ac} (\cal{ac}) [\cal{ac}) [[\cal{ac} (\cal{ac}) [[\cal{ac} (\cal{ac}) [[\cal{ac} (\cal{ac} (\cal{ac}) [[\cal{ac} (\cal{ac}) [[[\cal{ac} (\cal{ac}) [[[\cal{ac} (\cal

6 Beyond linearity

What problems are we trying to solve?

Our rheology experiments are performed rather gently so we do not end up in "non-linear" domains where the standard analysis tools fail. Our real world formulations often operate within non-linear domains so ideally we would routinely be experimenting in these wilder areas.

This is a very, very short chapter.

Our real-world formulations are likely to be subjected to large stresses and strains. Yet our rheological measurements generally stay in a comfortable range of small stresses and strains - for good reason. The theories make sense within small stresses and strains where the elastic response is linear. The G' and G'' analyses that we use most often are very clearly limited to small strains so any standard analysis falls apart when the amplitudes get large enough to represent real-world stresses and strains.

6.1 LAOS

Most modern rheometers can now carry out Large Amplitude Oscillatory Shear (ŠŒUÙ) { $\infty \cdot 1^{+}$ ($^{+} \cdot 1^{+} \cdot 1^{$

If a LAOS expert thinks that this chapter should be greatly expanded, to allow the technique to be explained to a wider audience, I would be delighted to work with them to make it happen.

7 Particle rheology

What problems are we trying to solve?

We already have the rheological methods that apply just as much to particulate

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 $V@^ { [\bullet c \& [{ { [} ^ ~ ~ eci [} ~ [+ a^{\bullet} & +ai] * c@^ ^ ^& c [~ i \bullet O [~ *@^+c^ES+i^*^+c] O thers, such as the one from Pal, may or may not be superior in some ways, but again it hardly matters for our real-world formulations of imperfect particles:$

Equ. 7-1 $\eta = \eta_0 \left(1 - \frac{\varphi}{\varphi_m} \right)^{-2.5\varphi_m}$ V@^ å {] [lcæ } c] [å } c å • c@æc æ • æ]] " T PRVWD

systems in the 2-3 range give lower yield stresses than systems with bad dispersants in the 8-10 range. The particle radius is r, with smaller particles, other things being equal, giving a higher yield strength as our instincts tell us. The constant k is my fudge value to provide plausible results. A screenshot of the relevant app follows shortly because it is incorporated into the high-shear app thanks to the commonality of many of the key inputs and calculations.

Œ | c@ [* @ c@^ ^ ^&c• [~ c@^ ä } c^ !æ&cä[} ^ }^!*^ æ } å !æåä • æ!^ ä {] [!cæ } c (] ! [] [!cä[}æ | c[Ò æ } å FÐ! !^•]^&cäç^|^) c@^ àā**^•c ^ ^&c ā• c@^ !æ]āå !ã•^ ¸ãc@ æ• āc •cæ !c• c[æ]] ! [æ&@ mÈ Ù[]æ^ã } * æcc^ }cã[} c[• { æ|| &@æ } *^• ā } &&e } be more rewarding than worrying too much about E or the meaning of r in a • ^•c^ { ¸ãc@ æ !æ } *^ [~]æ!cã&|^ •ã:^•È Q~

7.2 High Shear

 $Y^{\} [c@xc ci+&[+ic^ * [^+ c[@i*@|^c/+ xc|[, e@^x+ x]* @i*@ EV@i+, ['|a] mean that high-solids formulations would be impossible to handle. Fortunately, they shear-thin strongly, though caution is required because at very high shear rates some formulations can shear thicken alarmingly.$

 $\eta = \gamma^{n-1}$ and $n = \frac{\left(\frac{\varphi}{\varphi_m}\right)^{2/3} - 1}{\left(\frac{\varphi_c}{\varphi_m}\right)^{2/3} - 1}$

Other elements of the equation are described in the app - which we need because it is hard to grasp what such an equation will produce. The results turn out to be rather straightforward, at least when viewed as a log plot:

App 7-2 <u>https://www.stevenabbott.co.uk/practical-rheology/High-Shear-Particles.php</u>

V@^ •c

•|ãå^]æ•c ^æ&@ [c@^lÈ V@^ ^ ^&c ã• { [å^||^å à î ã}&!^æ•ã} * m with shear rate, an ^ ^&c ¸ ^||Ëçæ|ãåæc^å ã} c@^ |ãc^læcčl^È

If you decrease the Fractal Dimension from 3 (i.e. the system is no longer] `!^]æ!ci&|^•) æ}å å}&!^æ•^ $\dot{PE} c@^ }` {a^! [~]æ!ci&|^• i} æ '[&E c@^ ci•&[•ic^$ increases sharply. How do you know the fractal dimension and the number $[~]æ!ci&|^• i} æ '[&Ñ 0} *^}^!æ|_^ å[}'cE V@^ Ói&^!æ}[]æ]^!²⁶ from which I$ extracted the relationship tells us that a platelet formulation has a dimension of 2, $•[æ}^ }[!{æ||^ '[&&`|æc^å •^•c^{ }, i|| à^•[{^c@i}*|i^{\circ} GEIE ,@i&@ i• c@^ å^-æ`|c$ used in some of the graphs in that paper. In terms of N, you have to decide $<math>_{,@^c@^! c@^ •@^{a!} •c!^{-•o} æc æ@i*@ P cæ!^{a!} i^{|i^{\circ}|} c[_ii] c@^ '[&&`|æc^å$ $]æ!ci&|^• æ]æ!c[!E æ• &[]~`•i}*|^@æ]]^}•E {æ\^• ~`!c@^! '[&&`|æci]} {[!^|i^{\circ}|}^*$ $æ• _^ i]| åi•&`•• •@[!c]^E V[^c]|[!^c@^^ ^&ce^Ecæ]`^• [~P -![{ GEI •^^ { c[à^ reasonable.$

Why do particulate systems shear thin so much? It is because the shear drives $(@^]#!(i\&|^{\bullet} i)([]^{m}(i)^{\bullet} |i|^{\bullet} c^{0}i\&|^{\bullet} '[]i a [] c@^ |# }^{\bullet} [- # @i^{0}] a^{0}] a^{0} c^{0}i\&|^{\bullet} '[]i a [] c@^ |# }^{\bullet} [- # @i^{0}] a^{0} c^{0}] a^{0} c^{0} c^{0}i\&|^{\bullet} c^{0}i&|^{\bullet} c^{0}i&$

Why do some systems, after shear thinning as normal, shear thicken at very high $\mathbb{Q}^{2} + \mathbb{Q}^{2} + \mathbb{Q}^{$

7.2.1 Increasing m

Instead, the standard trick for our mostly-spherical formulations is to make sure $c@ac \bullet \{ae||^{1} acia|^{0} i\} c@^{-[1} \{aeia|^{0} aeia|^{0} ae$

²⁶ Jozef Bicerano, Jack F. Douglas, and Douglas A. Brune, *Model for the Viscosity of Particle Dispersions*, Journal of Macromolecular Science, Part C, 39:4, 561-642

For a simple binary distribution it is wellknown that there is an optimum size ratio and an optimum ratio of small to large particles. For a 10:1 size ratio with 33% of $c@^{A}$

App 7-3 https://www.stevenabbott.co.uk/practical-rheology/distribution.php

Here we have a rather unlikely distribution, created only for visual convenience. We have a large number of 300nm particles and a set at 1000nm of half the number (the relative "Height" values are 100 and 50). They are the same 100nm nominal width. The yellow "N" for Number curve shows exactly what I have just $a^{4} \cdot a^{1}a^{2} = \sqrt{2} \cdot \sqrt{2} \cdot \sqrt{2} = \sqrt{2} \cdot \sqrt{2$

Now look at the M for Mass (or it could be V for Volume) curve. There is a tiny peak around 300nm and a huge one at 1000nm. The cumulative curve tells us that only 6% of the mass is below 400nm and the 94% is above 900nm. The A for Area curves are in between.

So what is "the" size of these particles. If you take the volume average, ("mean diameter over volume"), this is ... And here we hit a typical problem. We have $-\frac{3}{4}, \frac{3}{2} = -\frac{1}{2} + \frac{1}{2} + \frac{1$

] ¦^~^¦ æ åä ^¦^} åä ^¦^}

7.4.1 The Péclet number

You often come across the Péclet number, Pe, in discussions of particles and shear rates. This dimensionless number describes the ratio of the movement $\hat{a} = \hat{a} = \hat{$

Equ. 7-4
$$Pe = \frac{r^2 \gamma}{D} = \frac{6\pi \eta r^3 \gamma}{kT}$$

App 7-5 https://www.stevenabbott.co.uk/practical-rheology/Peclet.php

7.5 Shear thickening

When we pour a somewhat viscous cornstarch dispersion into a bath it is a reasonably normal liquid, yet if we try to shear it suddenly by jumping on to it and swiftly walking, it is highly viscous, i.e. it has shear thickened. If we pause to $|^{\circ} \otimes [] c@^{\circ} { \ } & e^{i} \\ |^{\circ} \otimes [] c@^{\circ} { \ } & e^{i} \\ |^{\circ} \otimes [] c@^{\circ} { \ } & e^{i} \\ |^{\circ} \otimes [] c@^{\circ} \\ |^{\circ} \otimes [] c@^{\circ$

The main problem with the classic explanation for shear thickening is that it can be argued both ways (and often is).

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To argue the opposite, take a fairly concentrated dispersion and add extra energy via shear. This forces the particles into more intimate contact than they $\{\hat{a}^* \otimes c \mid \hat{a} \setminus \hat{c} \in \hat{a} \mid \hat{c} \otimes \hat{c} \in \hat{c}$

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It turns out that most systems show both types of behaviour, with the shear $c@\hat{a} \\ \hat{a} \\$

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How do you stop shear thickening from happening? The hydroclusters can [\rangle]^ ~[$|\{ \ 0^{\circ}\} c_{0}^{\circ}\rangle a_{1}^{\circ} a$

If you really want to understand all this then you need a good Stokesian Dynamics program, Apparently it all makes sense if you do. Ever optimistic I wondered if I could create a good-enough Stokesian Dynamics app. It seems that it is way beyond my capabilities and the processing power available to a typical app.

7.6 Can we apply particle rheology to the real world?

I once had to give a training course on topics that were to be applied to highly, $||^{a}] \approx \frac{1}{2} \frac{1}{2}$

training, I was struck by how useful it was to be able to keep going back to the principles contained in the apps, along with the key principles of entanglement $a^{a}_{a}^{$

 $\begin{array}{l} (E \bullet \left[\left[-c^{A} \right] \otimes \left[\right] \right]^{\bullet} \left[\right] \bullet \left\{ \frac{A}{A} \right\} & \left[\left[\left\{ A^{A} \right\} \right]^{\bullet} \left[\left\{ A^{A} \right]^{\bullet} \left[\left\{ A^{A} \right]^{\bullet} \left[\left\{ A^{A} \right\} \right]^{\bullet} \left[\left\{ A^{A} \right]^{\bullet} \left[\left\{ A^{A} \right\} \right]^{\bullet} \left[\left\{ A^{A} \right]^{\bullet} \left[\left\{ A^{A} \right]^{\bullet} \left[\left\{ A^{A} \right\} \right]^{\bullet} \left[\left\{ A^{A} \right]^$

Any models that are simple enough for me to understand and appify are unlikely to be a perfect representation of a complex system. What they do is allow "science-based formulation". Instead of saying "Increasing particle concentration increases viscosity and yield stress" which is both true and rather unhelpful, we can say "Increasing particle concentration over this range of concentrations will tend to have *these* $^ Acc \cdot a$ a c[&[cl [cl A - i] A c - i] parameters A, B and C. Because parameters A and B are not, for various reasons, adjustable, that means we must focus on C. So what do we know about C in this case ..."

So the answer to the question in this section is a clear: "Yes".

8 Summary

This is a guide, not a book. It represents what I wish I had known over my formulation career. My hope is that it brings out a few messages about which I am passionate.

- Measuring a few viscosities or even a few G':G" values is not good enough ā~ ^[`,æ}cc[[]cã {ã:^ ^[`|~[! { `|æcã[} ^ &ã^}c]^ [! &!^æc^ ã { æ*ã}æcãç^ }^, types of formulations.
- Rheologists do us and themselves a great disservice by choosing to create a bewildering number of plots of the "same" basic measurement. They should be encouraged to plot fewer variants in order to reach a more appreciative audience. And we should use the apps to help translate between confusing plots
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 with the downside that we can get swamped by alternatives. So we need to think about the links between key formulation properties and the measurements that can provide insights.
- A lot of polymer-based formulation and associated rheology can best be `}å^!•c[[å çiæ ^}cæ}*|^{{ ^}cE V@i• •@[,• `] i} åi ^!^}c~[!{ • i} ![cæci[]æ| and oscillatory rheology
- Q}c^!&[}ç^!•i[]• à^c,^^} (æc |^æ•c) Î åi ^!^}c ,æ^• [~|[[\i]* æc c@^ •æ {^ data should become standard for all of us. The interconversion app is one indication that this is both possible and desirable.
- We tend not to think in terms of timescales and the processes that control them. With a few ideas such as Deborah number and WLF and with measured timescales from oscillatory and thixotropic techniques we can à^cc^l `}å^l•cæ}å @[c[[]ci {i:^ c@^ &[}'i&ci}* å^{ {æ}å• [~ åi ^l^}c]ælc• of our real-world processes, especially via relaxation spectra.
- Interconversions should allow us to mix-and-match types of measurements c@æc @æç^ c@^åi [, } |å { åcæcå [} Ê æ|| [, å } * `• c[, || [č [`! ` } å^i cæ } åi } * [~ our formulations over a wider range of timescales to better understand performance across a range of real-world processes.
- The trick of providing guesstimates of shear rates and timescales allows us to know from our measurements what our key properties will be under those conditions, or to extend our measurement range in order to determine them.
- Our inability to map between rotational, oscillatory and elongational measurements is deeply unfortunate and a grand challenge to rheologists
- Particle-based formulations can be made more comprehensible via a small set of key parameters.

Because this is an eBook, I will be delighted to update, revise, correct errors, or write new apps. I can only do this with your help. Feel free to email, phone, $V_{,}^{c} [|\check{S}i| \wedge a0] \stackrel{E}{=} [\check{R}a] \wedge a0$